

9. The refuse vehicle of claim 1, further comprising position sensors capable of determining the position of the refuse loader.
10. The refuse vehicle of claim 1, wherein an operator inputs the position along the path.
11. The refuse vehicle of claim 10, wherein the position is stored in memory.
12. The refuse vehicle of claim 1, further comprising a graphical interface capable of displaying the refuse loader's position as it moves along the path.
13. The refuse vehicle of claim 12, wherein the graphical interface displays the refuse loader's position using numerical percentages or by displaying a graphical representation of the refuse loader.
14. The refuse vehicle of claim 13, further comprising arms and forks, wherein the graphical interface displays the position of the arms or forks.
15. The refuse vehicle of claim 1, wherein the load is a refuse receptacle.
16. The refuse vehicle of claim 1, further comprising arms and forks.
17. The refuse vehicle of claim 16, further comprising position sensors capable of determining the position of the arms or the forks.
18. A refuse vehicle comprising:
 - a refuse loader, the refuse loader being capable of moving a load along a path and into the refuse vehicle; and
 - an electronic control system capable of controlling movement of the refuse loader along the path;
 - wherein the refuse loader controlled by electronic control system is capable of:

